

Straight Skeleton Implementations based on Exact Arithmetic

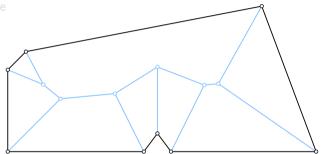
Günther Eder, Martin Held, and Peter Palfrader



Online Conference, March 2020

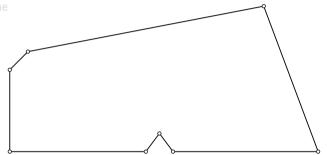


- Defined as a result of a *wavefront propagation*.
- The *Straight Skeleton* is the trace of the vertices of the wavefront over time.
- Edge Events, Split Events.
- Applications: Tool path generation



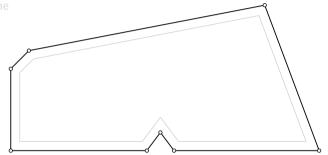


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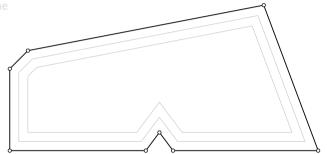


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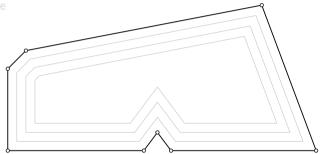


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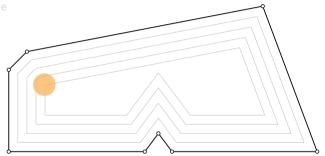


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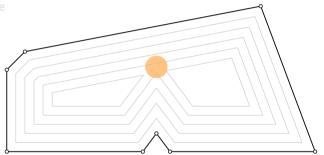


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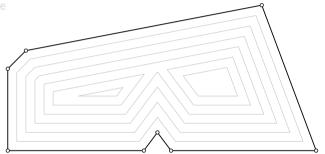


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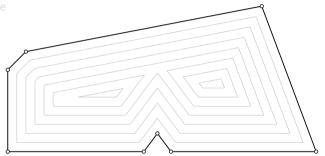


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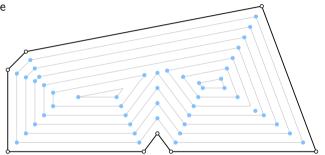


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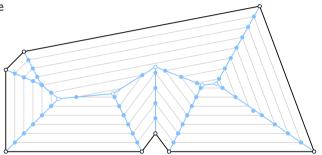


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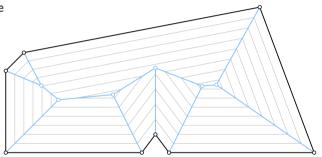


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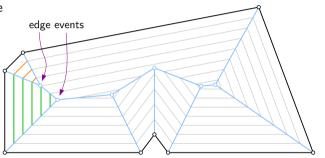


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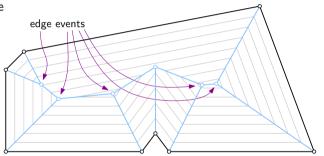


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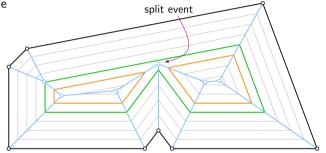


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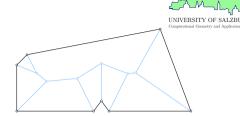


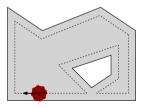


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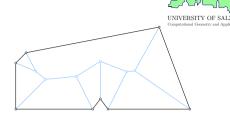


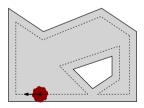
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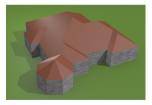




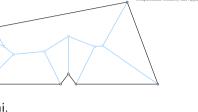
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- Applications: Tool path generation, Roof modeling

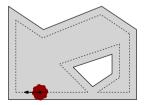


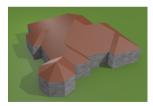


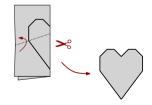


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Best worst-case complexity:

• Eppstein and Erickson (1998) and Cheng et al. (2016).

With implementations:

- Cacciola (2004), based on Felkel and Obdržálek (1998).
- Aichholzer and Aurenhammer (1998)*.
- For monotone polygons: Biedl et al. (2015)*.



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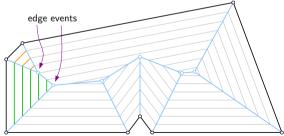
- Input: polygons and polygons with holes.
- Priority queue of edge events and all *potential* split events.
- There are quadratic many such *potential* split events.



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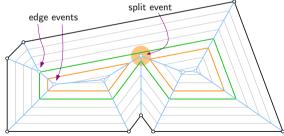


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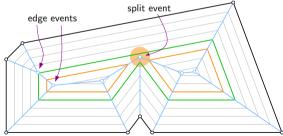


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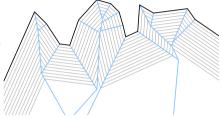


- Input: (strictly) monotone polygons.
- Key Observation: A monotone chain never splits.
- Idea: Compute the straight skeleton of two chains, then merge them.
- Runtime: $\mathcal{O}(n \log n)$.

- New implementation: Monos.
- Also works on *not-strictly* monotone polygons (tricky in the merge step).



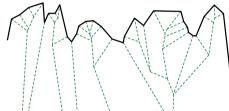
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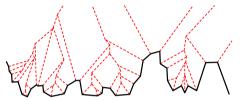
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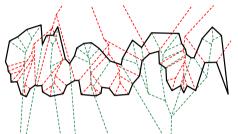
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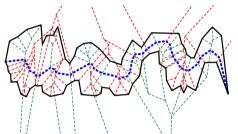
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• Input: PSLGs. Can compute the weighted straight skeleton.

- Uses a kinetic data structure to witness events: Triangulate the not-yet-swept plane; triangles witness events
- There are only linear many *real events*. However, there might be $O(n^3)$ flip events.

- New implementation: SURFER2.
- Several special cases not considered in the original paper.

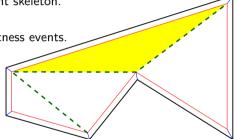


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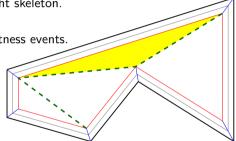
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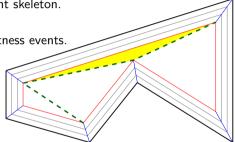
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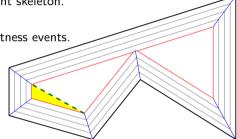
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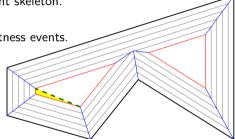
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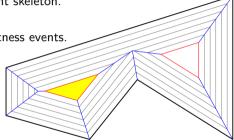
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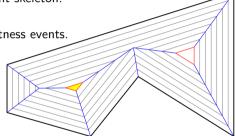
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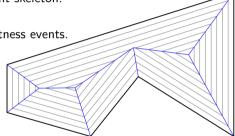
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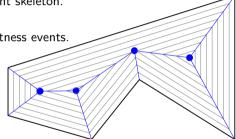
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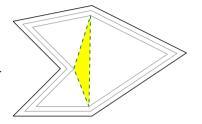
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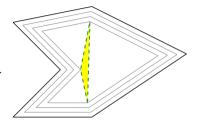
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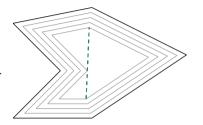
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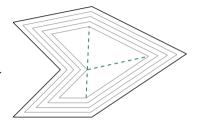
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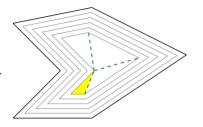
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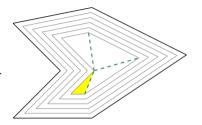
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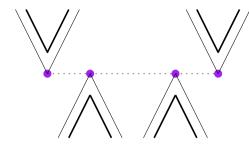
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Some Special Cases

- Flip-event Loops.
- Vertices meeting along triangulation edges.
- Wavefront edges moving into each other.
- Collinear wavefront segments of different speeds becoming adjacent.

Implementation Considerations

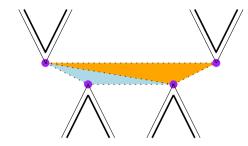


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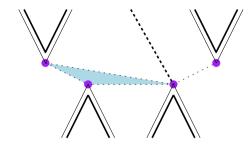


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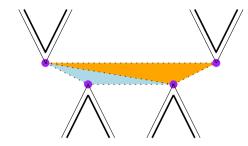


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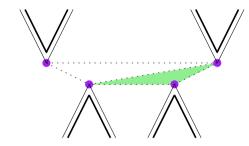


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- Collinear wavefront segments of different speeds becoming adjacent.

Implementation Considerations

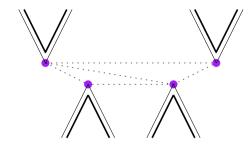


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Some Special Cases

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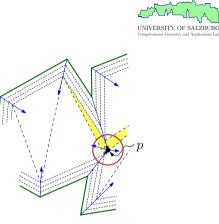
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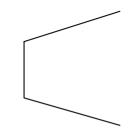
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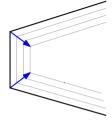


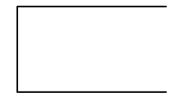
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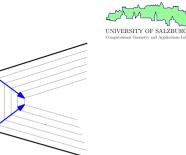




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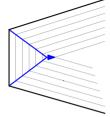


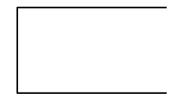
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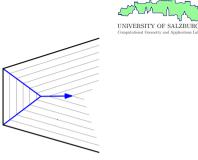




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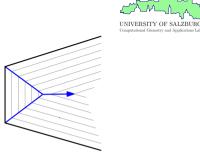


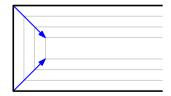


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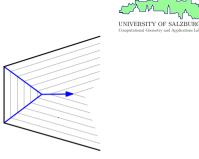


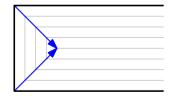


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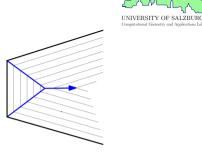


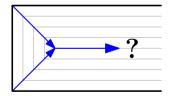


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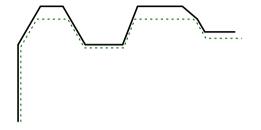




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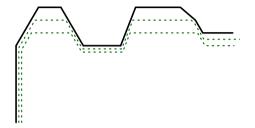




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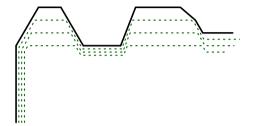




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Implementation Considerations



$\operatorname{Surfer2}$

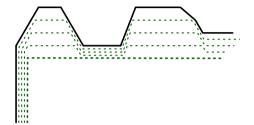


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• Event classification: Where possible, rely on combinatorial/discrete information instead of doing computations on reals.



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$\operatorname{Surfer2}$

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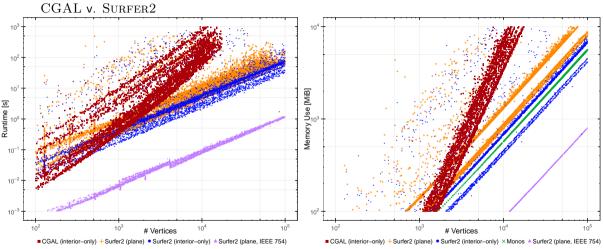
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Runtime

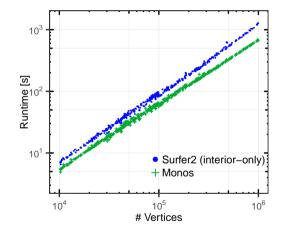




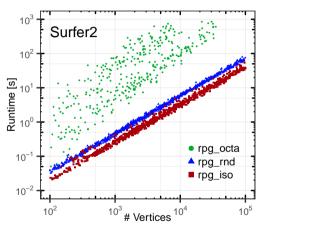
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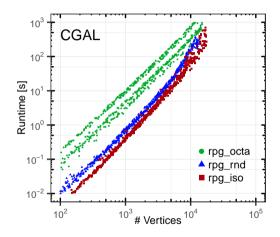


Monos V. Surfer2

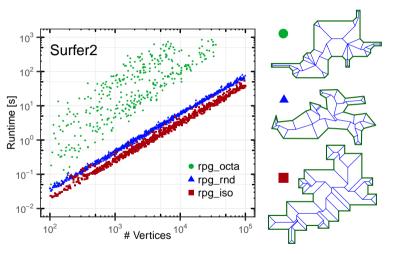








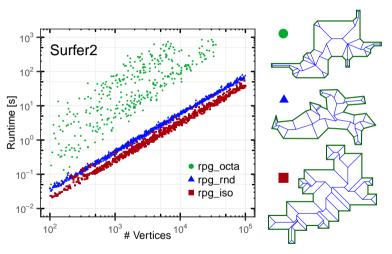




• Why is iso less problematic than octa input?

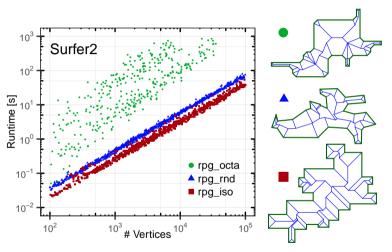
- Turns out our octa input was on the integer grid, the iso had random coordinates.
- This resulted in significantly many co-temporal events for the octa input.
- Indeed, with random edge weights, the spread goes away.
- We can split triangles by component, as the skeletons are independent.





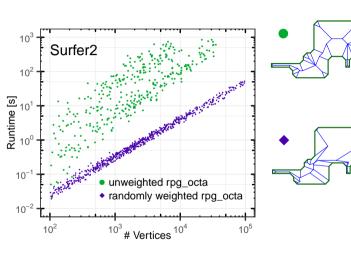
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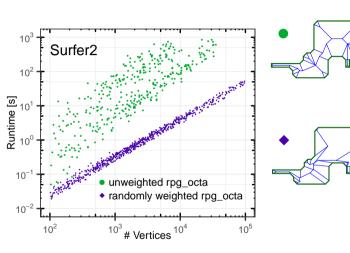
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- MONOS: https://github.com/cgalab/monos
- SURFER2: https://github.com/cgalab/surfer2

Thanks!

Questions? Mail palfrader@cs.sbg.ac.at



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